

## DEPLOYMENT LOG for IceCube STRING # 56

Deployment Start:	at	10:12	on	_1	128	107	
				1	/		

Target depth (DOM60): 2450 m Final depth: 2451.04

**Deployment Crew** 

Position	First Shift	Second Shift
Shift lead	A. KARLE	T. HAM
DOM install 1 (high)	G. KOHNEN	, i
DOM install 2 (low)	P. ROTH	
DOM supply 1 / DOM install 3	C. PETERSON	iven
DOM supply 2 / floater	5, B'ENSER	
Winch operator (cable & tower)	>0. BLYTHE	<i>u</i>
Notary (logbook & photos)	M. DIAGOSTINO	Justin
PTS (monitoring / sensors)	M. 0/A60577NO	. 4

	shift change:	79/20	1
54	9 lus	7	1 ho
	7		
	lanur	and the	

Hole Handover		
☐ Drill data reviewed		
□ maximum drift in	x: □ plot	
☐ maximum drift in	y:	
☐ maximum depth:_	·	
☐ minimum radius:_	□ plot	
□ plot of predicted r	adius vs depth and time	8
☐ Hole dimensions veri	fied	Time:
Drill Lead:	name / signature / date	
Deployment Lead: _	name / signature / date	· · · · · · · · · · · · · · · · · · ·
	☐ Handover complete	a a
0 0	e a	
Hole Logging (skip if not applicable)		
☐ Logger drop started	Time: Speed: Speed: Speed:	9 
<ul><li>□ Logging started</li><li>□ Logging ended</li></ul>	Time: Speed:_ Time:	
☐ Estimated hole lifetim	ne.	

► Must reach target depth by \_\_\_\_\_ on \_\_\_\_



Deployment Startup				
Time:				
☐ Cable winch anchored and ☐ operational ☐ Tower winch operational				
☐ Tie off verified ☐ Yellow rope verified				
Deployment monitoring system (PTS) operational DDB#_3				
Bleeder string installed (on quad connectors inside cable reel drum)				
☐ Uphole pressure system on hand: Setra sensor and cable				
<ul> <li>☑ DOMs placed in racks</li> <li>☑ Weight stack on hand: weights (5) and 2 m cable</li> <li>☑ 17 m string extension steel cable on hand</li> </ul>				
Safety checks complete ( 1st shift  2nd shift)  Crew safety briefing  E-stop locations identified  TOS evacuation procedures reviewed  Mustering point identified  Snow mobile driver(s): PHOSTINO CEST				
☐ CPR trained: KLEIST, ROTH ☐ Food runners:				
End of Main Cable brought into TOS and secured				
Cable end attachments				
☐ Measure well depth: 52,598  Weights (5) attached				
Weight cable attached (weight stack complete) Time: /0:15				



Photos: DOM ids ( long   short); connectors ( long   short)  DOM position 60  DOM id: TP 4P0067				
DOM pos	sition 60	DOM id: TR 4P0067		
(T, Long)				
☐ Top s	m shackle connected to weight stack hackle connected to 17 m steel cable   ☐ whole view	Payout: 0,00		
DOM pos	sition 59	DOM id: UP <u>5H 0/7</u> (,		
(U, Short)	Cable mark: 1,5 m			
☐ Top s ☐ Main	m shackle connected to 17 m cable hackle connected to Yale grip cable end taped to 17 m steel cable □ phi orientation □ whole view	Δ(59-60): 17, 86/ (use laser ranger)		
Breakou	t 30	Time: 11: 60		
□ br	DOM onnector O-ring in place and □ lubed eakout O-ring in place and □ lubed onnected	Depth: Payout_21,65		
□ br	DOM onnector O-ring in place and □ lubed eakout O-ring in place and □ lubed onnected			
□ Loose	e pigtails taped to cable	«		
Paro	Serial #: 98/08 Nipple   on   Connected   Operational   Air   Cable mark:   Distance	off pressure [PSI]: 8.55		
_	_ Caule mark   Distance	alma Dom 59		
<i>9</i> 9	□ <b>A</b> II alaa ta laa	ole @ 18,669 to Dom 66		
	□ All clear to lower cal	DIE () 10/40/ 40/00/40		





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 58	DOM id: TP_590615	
(T, Long) Cable mark:		
Bottom shackle connected  Top clutch connected at link #	Δ(58-59)://, 802	
DOM position 57	DOM id: UP <u>5 H 0 1 0</u> 2	
(U, Short) Cable mark: 35		
<ul> <li>□ Bottom shackle connected</li> <li>□ Top clutch connected at link #_20</li> <li>□ Bow OK → □ clutch zip tied</li> <li>Photos: □ phi orientation □ whole view</li> </ul>	Δ(57-58): 16.902	
D14-20	Time	
Breakout 29	Time:	
a i	Now_//:20	
- LongDOM	Last b/o	
☐ connector O-ring in place and ☐ lubed	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
□ connected	Paro 71.26 Payout 52,43	
- ShortDOM	1 ayout	
$\Box$ connector O-ring in place and $\Box$ lubed		
☐ breakout O-ring in place and ☐ lubed		
□ connected	*	
☐ Loose pigtails taped to cable		
e some second	*	
□ All clear to lower cal	ole 😊	





Photos: DOM ids (□ long □ short); connector	s (□ long □ short)
DOM position 56	DOM id: TP <u>5P098</u> 7
(T, Long) Cable mark: 53	
Bottom shackle connected  Top clutch connected at link #/8 Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(56-57): 16,932
DOM position 55	DOM id: UP 5 P 0 6 7 4
U, Short)  Cable mark:   Bøttom shackle connected  Top clutch connected at link # 20  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(55-56): /6,858
Breakout 28	Time:
<ul> <li>LongDOM</li> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul>	Now //: 3/  Last b/o  Δt [min]  Depth:  Paro 86,79  Payout 86,34
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
☐ Loose pigtails taped to cable	
	N.
□ All clear to lower ca	ıble 😊

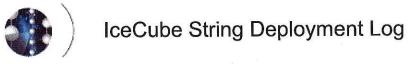




Photos: DOM ids (	$\square$ long $\square$ short); connectors	$s ( \Box \log \Box \text{ short})$
	iong is short, competer.	DOM id: TP 644357
DOM position 54 (T, Long)	Cable mark: 86	DOWNG. II Wy 1000
(T, LONG)	Cable mark. 00	- × ×
☑ Bottom shackle c		
/ -	eted at link #/8	Δ(54-55): /6.9/9
Bow OK → Cl	1	
Photos: $\square$ phi orien	tation   whole view	
DOM position 53		DOM id: UP 5906.90
<b>DOM position 53</b> (U, Short)	Cable mark: 103	<b>DOM Id.</b> 01 <u>3106/0</u>
(0, 3)(0)()	Cable mark. 100	
☑ Bottom shackle c		
/ -	octed at link #_ 20_	Δ(53-54): 16,925
Bow OK → Vcl	200 Page 1	à
Photos: ☐ phi orien	tation □ whole view	
Breekeut 27		Time:
Breakout 27		
a a		Now_11:45
- LongDOM		Last b/o
	ring in place and □ lubed	Δt [min]
ONT	$\log$ in place and $\square$ lubed	Depth:
□ connected		Paro <u>MWW / 3 9 17 7</u> Payout ) 3 2 4
ChartDOM		Payout 129127
- ShortDOM	ring in place and □ lubed	
II.	$ling in place and \square lubed$	
□ connected	ing in place and - laced	
☐ Loose pigtails tap	ped to cable	
	**************************************	



Photos: DOM ids (□ long □ short); connectors	s (□ long □ short)
DOM position 52	DOM id: TP 69/265
Top clutch connected at link # 18  Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view	Δ(52-53): /6, 980
DOM position 51 (U, Short) Cable mark: 137	DOM id: UP <u>691308</u>
<ul> <li>□ Bottom shackle connected</li> <li>□ Top clutch connected at link #_ Q0_</li> <li>□ Bow OK → □ clutch zip tied</li> <li>Photos: □ phi orientation □ whole view</li> </ul>	Δ(51-52): 16,874
Breakout 26	Time:
<ul> <li>LongDOM</li> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul> ShortDOM	Now //:55  Last b/ο Δt [min]  Depth:  Paro /54,/8  Payout /5/,70
<ul> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul>	* = .
☐ Loose pigtails taped to cable	
☐ All clear to lower cab	ole ⊙



Photos: DOM ids (	☐ long ☐ short); connectors	
DOM position 50		DOM id: TP 47 007/
(T, Long)	Cable mark: 154	AP
(1, Long)	Sabio mark	2
☑ Bottom shackle	connected	
Top clutch conn	ected at link # 18	Δ(50-51): 16.974
Bow OK → Do		_
Photos: □ phi orie	ntation $\square$ whole view	2.5
	around DOM:	Vertical distance:
<b>DOM</b> position 49		DOM id: UP <u>54-015-4</u>
(U, Short)	Cable mark: 17	
//	*	
■ Bottom shackle		1/ 070
/ -	ected at link #_20_	Δ(49-50): // <sub>2</sub> , 878
$\square \text{Bow OK} \to \square C$		
Photos: ☐ phi orie	ntation □ whole view	**************************************
☐ Curved distance	e around DOM:	Vertical distance:
Breakout 25		Time:
Dieakout 25		4
		Now 1:25 (after lune
- LongDOM		Last b/o
□ connector O	ring in place and □ lubed	Δt [min]
□ breakout O-	ring in place and $\square$ lubed	Depth:
$\Box$ connected		Paro 189,36
		Payout 187.87
- ShortDOM		
□ connector O	ring in place and □ lubed	
	ring in place and $\Box$ lubed	
□ connected		u 2
2		
☐ Loose pigtails ta	aped to cable	
	,	
	☐ All clear to lower ca	ble ⊕





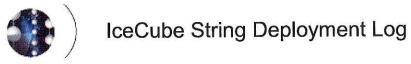
Photos: DOM ids ( $\square$ long $\square$ short); connector	's (□ long □ short)
DOM position 48	DOM id: TP <u>644363</u>
(T, Long) Cable mark: <i>188</i>	
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #_/8</li> <li>☑ Bow OK → ☑ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(48-49): <i>16,999</i>
DOM position 47	DOM id: UP <u>5P1038</u>
(U, Shørt) Cable mark: 205	<u> </u>
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #</li></ul>	Δ(47-48):_ <i> \big </i> ,92
Breakout 24	Time:
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now 1:35  Last b/o  Δt [min]  Depth:  Paro 223,08  Payout 217,61
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
☐ Loose pigtails taped to cable	
☐ All clear to lower ca	ıble ©

IceCube String Deployment Log	String 56
Photos: DOM ids ( $\square$ long $\square$ short); connector	$s (\Box long \Box short)$
DOM position 46	DOM id: TP 4P0263
(T, Long) Cable mark: 222	
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #/8</li> <li>☑ Bow OK → ☐ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(46-47): <u>/6,940</u>
DOM position 45	DOM id: UP 69/276
(U, Short) Cable mark: 234	
Bottom shackle connected  Top clutch connected at link #	Δ(45-46): <u>/6,882</u>
Breakout 23	Time:
9	Now 1.45
- LongDOM	Last b/o
☐ connector O-ring in place and ☐ lubed	Δt [min]
☐ breakout O-ring in place and ☐ lubed	Depth:
□ connected	Paro <u>357.37</u>
Class#DOM	Payout_251.00
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
☐ Loose pigtails taped to cable	





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
<b>DOM position 44</b> DOM id: TP <u>5 P 0905</u>		
(T, Long) Cable mark: 256		
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link # / 8</li> <li>☑ Bow OK → ☑ clutch zip tied</li> </ul>	Δ(44-45): <i> </i> 6, <i>936</i>	
Photos: □ phi orientation □ whole view	n a a	
DOM position 43	DOM id: UP <u>69 /220</u>	
(U, Short) Cable mark: 373	, *	
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #_20</li> <li>☑ Bow OK → ☑ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(43-44): /6.883	
rhotos.   pin orientation   whole view		
Breakout 22	Time:	
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now /:55  Last b/o Δt [min]  Depth:  Paro 291.77  Payout 284.34	
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected		
☐ Loose pigtails taped to cable		
20 E		
	a service and the service and	
□ All clear to lower cal	ole ©	



Photos: DOM ids ( $\Box$ long $\Box$ short); connectors ( $\Box$ long $\Box$ short)		
DOM position 42		DOM id: TP <u>540/0</u> 7
(T, Long)	Cable mark: 290	8 7
☑ Bow OK → ☑ cl	ected at link #/8	Δ(42-43): <u>/6,999</u>
DOM position 41		DOM id: UP <u>5 14 024</u> 8
(U, Short)	Cable mark: 307	<u> </u>
Bottom shackle of Top clutch connection OK → □ cl	connected ected at link #20	Δ(41-42): <u>/6,905</u>
Breakout 21		Time:
<ul><li>□ breakout O-r</li><li>□ connected</li><li>- ShortDOM</li><li>□ connector O-</li></ul>	ring in place and □ lubed ing in place and □ lubed ring in place and □ lubed ring in place and □ lubed ped to cable	Now 2:02  Last b/ο Δt [min]  Depth:  Paro 325.58  Payout 3/7.31
		6
a v		
w		
	☐ All clear to lower cal	ble ☺



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 40	DOM id: TP <u>644447</u>	
(T, Long) Cable mark: 324		
Bottom shackle connected  Top clutch connected at link #/8  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(40-41): 16,928	
DOM position 39	DOM id: UP <u>5 40 / 44</u>	
(U, Short) Cable mark: 340		
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #</li></ul>	Δ(39-40): / <i>(<sub>6</sub>, 9 05</i>	
Breakout 20	Time:	
<ul> <li>LongDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> <li>ShortDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> <li>Loose pigtails taped to cable</li> </ul>	Now 2:/0  Last b/o Δt [min]  Depth: Paro 359.85  Payout 350,51	
□ All clear to lower ca	ble 😊	





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)	
DOM position 38	DOM id: TP <u>69124</u> 7
(T, Long) Cable mark: 357	
□ Bottom shackle connected □ Top clutch connected at link #	Δ(38-39):/6,930_
DOM position 37	DOM id: UP 691208
(U, Short) Cable mark: 374	<b>50</b> (11 ox <u>37 ) 1 ox</u>
Bottom shackle connected  ☐ Top clutch connected at link #	Δ(37-38): 16,905
Breakout 19	Time:
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now 2:20  Last b/o Δt [min]  Depth:  Paro 394.00  Payout 383.64
- ShortDOM  ☐ connector O-ring in place and ☐ lubed ☐ breakout O-ring in place and ☐ lubed ☐ connected	
☐ Loose pigtails taped to cable	
☐ All clear to lower cal	ble 😊





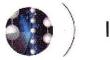
Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 36	DOM id: TP_5P1017	
(T, Long) Cable mark: 391	р.	
Bottom shackle connected  Top clutch connected at link #	Δ(36-37): 16,950	
DOM position 35	DOM id: UP 480296	
(U, Short) Cable mark: 408		
<ul> <li>Bottom shackle connected</li> <li>Top clutch connected at link #</li></ul>	Δ(35-36): <u>  [6,952</u>	
Breakout 18	Time:	
- LongDOM    connector O-ring in place and   lubed   breakout O-ring in place and   lubed   connected  - ShortDOM   connector O-ring in place and   lubed   breakout O-ring in place and   lubed   connected    Loose pigtails taped to cable   Put two Kellers (one is for backup) in bucket	Now 2:30  Last b/o  At [min]  Depth:  Paro 428//  Payout 4/6.8/	
□ All clear to lower cab	le 😊	



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 34	DOM id: TP 6 1255	
(T, Long) Cable mark: 425	· ·	
Bottom shackle connected  Top clutch connected at link #/8  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(34-35): <u>/ 6, 96 /</u>	
DOM position 33	DOM id: UP 5 P 0 5 0 0	
(U, Short) Cable mark: 442		
Bottom shackle connected  ☐ Top clutch connected at link #	Δ(33-34): <u>/6,920</u>	
Breakout 17	Time:	
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now 2,40  Last b/o  Δt [min]  Depth:  Paro 462,41  Payout 450.00	
<ul> <li>ShortDOM</li> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul>		
☐ Loose pigtails taped to cable		
□ All clear to lower cal	ble ☺	



Photos: DOM ids (□ long □ short); connector	rs (□ long □ short)
DOM position 32	DOM id: TP_4H00/4
(T, Long) Cable mark: 459	
Bottom shackle connected	
Top clutch connected at link #	Δ(32-33): 16,944
Thotos.   pin orientation   whole view	
DOM position 31	DOM id: UP <u>69 / 2/6</u>
(U, Short) Cable mark: 476	
Bottom shackle connected	
Top clutch connected at link # 20	Δ(31-32): 16-895
F	
Breakout 16	Time:
	Now 3:05
- LongDOM	Last b/o
<ul><li>□ connector O-ring in place and □ lubed</li><li>□ breakout O-ring in place and □ lubed</li></ul>	Δt [min] Depth:
□ connected	Paro 496.93
	Payout 483,43
- ShortDOM  ☐ connector O-ring in place and ☐ lubed	
□ breakout O-ring in place and □ lubed	
□ connected	
☐ Loose pigtails taped to cable	
□ All clear to lower cat	ole 😊



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)	
DOM position 30	DOM id: TP <u>59 10</u> 67
(T, Long) Cable mark: 493	
Bottom shackle connected  Top clutch connected at link # 18  Bow OK → clutch zip tied  Photos: □ phi orientation □ whole view	Δ(30-31): 16,937
DOM position 20	DOM id: UP <u>59072</u> 2
DOM position 29 (U, Short) Cable mark: 5/0	DOWIG. OF STOTAL
(U, Short) Cable mark: 5/0	
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #_20</li> <li>☑ Bow OK → ☑ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(29-30): 16,933
Breakout 15	
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
☐ Loose pigtails taped to cable	e 1
Thermistor       □ Present       □ Distance to DON         Keller       □ Connected       □ Operational         Ser.#:       □ Cable mark:       □ Dis	
□ All clear to lower ca	ble @ 106 29



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 28	DOM id: TP69/285	
(T, Long) Cable mark: 527		
Bottom shackle connected  Top clutch connected at link #/8  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(28-29): <u>/6.976</u>	
DOM position 27	DOM id: UP <u>5月0/4</u> ス	
(U, Short) Cable mark: 544	<u> </u>	
Bottom shackle connected  Top clutch connected at link #_20  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(27-28): 16,916	
Breakout 14	Time:	
<ul> <li>LongDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> <li>ShortDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> </ul>	Now 3:30  Last b/o  Δt [min]  Depth:  Paro 565.47  Keller 580.30  Payout 550.09	
☐ Loose pigtails taped to cable		
□ All clear to lower cab	le ⊚	



Photos DOM ida ( long   about), annuators	( long   short)	
Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 26	DOM id: TP <u>6P138</u> 7	
(T, Long) Cable mark: 56/		
☑ Bottom shackle connected	11 - 10	
☐ Top clutch connected at link # 18	Δ(26-27): 16,982	
□ Bow OK → □ clutch zip tied	e	
Photos: □ phi orientation □ whole view		
V a v		
DOM position 25	DOM id: UP <u>59056</u> 6	
(U, Short) Cable mark: 578	20	
□ Bottom shackle connected	i and	
☑ Top clutch connected at link # 20	Δ(25-26): <u>  [6,94]</u>	
Bow OK → □ clutch zip tied		
Photos: $\Box$ phi orientation $\Box$ whole view		
Breakout 13	Time:	
	Now_3/4/	
LangDOM	Last b/o	
- LongDOM		
☐ connector O-ring in place and ☐ lubed	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
	Paro <u>599,47</u>	
	Keller_400,12	
- ShortDOM	Payout 583./9	
□ connector O-ring in place and □ lubed		
$\Box$ breakout O-ring in place and $\Box$ lubed		
☐ Loose pigtails taped to cable		
er e		
v v		
☐ All clear to lower cal	ole 😊	



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 24 DOM id: TP 691309		
(T, Long) Cable mark: 595		
Bottom shackle connected  Top clutch connected at link #/  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(24-25): <u>/6,974</u>	
DOM position 23	BROKEN CONNECTOR DOM id: UP 69 1510	
U, Short) Cable mark: 4/2	DOM Id: 0P_07 / 3/0	
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #_ ② 0</li> <li>☑ Bow OK → □ clutch zip tied</li> </ul>	Δ(23-24): <u>//</u> ,888	
Photos: $\Box$ phi orientation $\Box$ whole view		
Breakout 12		
<ul> <li>LongDOM</li> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul>	Lasi Δt [:	
- ShortDOM	Pa	
<ul> <li>□ connector O-ring in place and □ lubed</li> <li>□ breakout O-ring in place and □ lubed</li> <li>□ connected</li> </ul>		
☐ Loose pigtails taped to cable		
	4	
□ All clear to lower ca	ble 😊	



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 22		DOM id: TP_5H0139
(T, Long)	Cable mark: ७३१	
Bottom shackle	connected	8
	ected at link #/8	Δ(22-23): /6,935
Bow OK → dcl	lutch zip tied	
Photos: ☐ phi orien	tation \( \subseteq \text{ whole view}	9
DOM position 21	*	DOM id: UP 5 P 1000
(U, Short)	Cable mark: 645	<u> </u>
☑ Bottom shackle of		
	ected at link #30	Δ(21-22): /6,9/6
Bow OK → I/cl		_(_ ·/ <u>////</u>
Photos: □ phi orien	tation $\square$ whole view	
Breakout 11		Time:
breakout i i		Some
I DOM		Now_4100
- LongDOM	ring in place and □ lubed	Last b/o Δt [min]
	ing in place and $\Box$ lubed	Depth:
□ connected		Paro 668.01
		Keller 668.88
- ShortDOM	المطيدا بالمعام معام ما ماسم	Payout 64995
	ring in place and $\Box$ lubed ing in place and $\Box$ lubed	
□ connected	mg m pawee and = 10000	
a and a second		á
☐ Loose pigtails ta	ped to cable	
2 2		
	☐ All clear to lower cal	ble ©



Photos: DOM ids (□ long □ short); connectors (□ long □ short)			
DOM position 20 DOM id: TP 64 427			
	ected at link #	Δ(20-21): <u>//6,990</u> Vertical distance:	
DOM position 19		DOM id: UP <u>59/06</u> 2	
(U, Short)	Cable mark: 479	30 m la. 01 <u>37 7 v v</u> v	
<ul> <li>☑ Bottom shackle</li> <li>☑ Top clutch conn</li> <li>☑ Bow OK → ☑ cl</li> </ul>	connected ected at link #_20	Δ(19-20): <u>/6,9</u> ೩ <u>6</u>	
-	around DOM:	Vertical distance:	
Breakout 10		Time:	
		Now_4://	
- LongDOM	e .	Last b/o	
□ connector O-	ring in place and □ lubed	Δt [min]	
☐ breakout O-r	ing in place and $\Box$ lubed	Depth:	
□ connected	i i	Paro 702.25	
<b>21 2 2 3 3</b>		Keller 762.75	
	ring in place and □ lubed ing in place and □ lubed	Payout_(283,38	
☐ Loose pigtails ta	ned to cable		
_ Loose piguins tu	ped to cable		
	□ All clear to lower ca	hla o	





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 18 DOM id: TP 69/295		
(T, Long) Cable mark: 697		
Bottom shackle connected  Top clutch connected at link # $/8$ $\Delta$ (18-19): $/(6,990)$ Bow OK $\rightarrow \Box$ clutch zip tied  Photos: $\Box$ phi orientation $\Box$ whole view		
DOM position 17 DOM id: UP 64 4324		
(U, Short) Cable mark: 113		
□  Bottom shackle connected $ □ $ Top clutch connected at link # $ 20 $ $ □ $ Bow OK $ → $ Clutch zip tied Photos: $ □ $ phi orientation $ □ $ whole view		
Breakout 9 Time:		
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected  - ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected  - Loose pigtails taped to cable		
□ All clear to lower cable ☺		

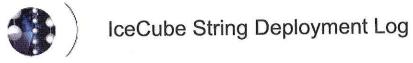




Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 16	DOM id: TP_5f099/	
(T, Long) Cable mark: 730	2 1 10	
Bottom shackle connected  ☐ Top clutch connected at link #/8 ☐ Bow OK → ☐ clutch zip tied  Photos: ☐ phi orientation ☐ whole view	Δ(16-17): <u> //<sub>4</sub>,928</u>	
DOM position 15	DOM id: UP 6P 1252	
(U, Short) Cable mark: 747		
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link # 20</li> <li>☑ Bow OK → ☑ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(15-16): <u>//, 890</u>	
Breakout 8	Time:	
<ul> <li>LongDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> <li>ShortDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> </ul>	Now 4:36  Last b/o  At [min]  Depth:  Paro 770.51  Keller 771.15  Payout 749.91	
☐ Loose pigtails taped to cable		
□ All clear to lower cal	ole ©	



Photos: DOM ids (□ long □ short); connectors (□ long □ short)			
DOM position 14		DOM id: TP 691259	
(T, Long)	Cable mark: 765		
Bottom shackle	connected		
/ /	ected at link #_/8	Δ(14-15): 16,954	
Bow OK → Jc	lutch zip tied	A CONTRACTOR OF THE CONTRACTOR	
Photos: □ phi orie	ntation   whole view		
DOM position 13		DOM id: UP <u>5H024</u> 0	
(U, Short)	Cable mark: 78	2 amountaine ann an t-	
Bottom shackle	connected		
	ected at link #_20	Δ(13-14): /6,9/8	
Bow OK → v c		1	
Photos: □ phi orie	ntation   whole view		
Breakout 7		Time:	
Dicarout i			
LangDOM		Now_ <i>4:45</i> Last b/o	
- LongDOM	-ring in place and □ lubed	Δt [min]	
	ring in place and $\Box$ lubed	Depth:	
□ connected		Paro 804.63	
		Keller 80 9.45	
- ShortDOM		Payout_783,//	
	-ring in place and □ lubed ring in place and □ lubed		
	ring in place and in labed		
☐ Loose pigtails ta	aped to cable		
	☐ All clear to lower cab	ole 😊	



Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 12 DOM id: TP 64 43		
(T, Long) Cable mark: 798		
Bottom shackle connected  Top clutch connected at link #/  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(12-13): <u>                                     </u>	
DOM position 11	DOM id: UP 5 P07 82	
(U, Short) Cable mark: 815		
Bottom shackle connected  Top clutch connected at link #_20  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(11-12): <u>16,902</u>	
Breakout 6	Time:	
<ul> <li>LongDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> <li>ShortDOM <ul> <li>connector O-ring in place and □ lubed</li> <li>breakout O-ring in place and □ lubed</li> <li>connected</li> </ul> </li> </ul>	Now 4:59  Last b/o Δt [min]  Depth:  Paro 839.50  Reller 839.50  Payout 8/6.79	
☐ Loose pigtails taped to cable		
	hlo. O	
☐ All clear to lower ca	DIE 😊	



DOM position 10  (T, Long)  Cable mark: \$32  ✓ Bottom shackle connected ✓ Top clutch connected at link # 18 ✓ Bow OK → ✓ clutch zip tied Photos: □ phi orientation □ whole view
(T, Long) Cable mark: $832$ Bottom shackle connected  Top clutch connected at link # $18$ Bow OK $\rightarrow \square$ clutch zip tied $\Delta$ (10-11): $16.953$
DOM position 9 (U, Short)  Cable mark: 849  DOM id: UP 64 4464
Bottom shackle connected  Top clutch connected at link # $20$ $\Delta(9-10)$ : $16,900$ Bow OK $\rightarrow \Box$ clutch zip tied  Photos: $\Box$ phi orientation $\Box$ whole view
Breakout 5
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected  - ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected
☐ Loose pigtails taped to cable
□ All clear to lower cable ☺





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 8	DOM id: TP <u>644479</u>	
(T, Long) Cable mark: 867	State of the State	
<ul> <li>□ Pottom shackle connected</li> <li>□ Top clutch connected at link # /8 Δ(8.</li> <li>□ Bow OK → □ clutch zip tied</li> <li>Photos: □ phi orientation □ whole view</li> </ul>	-9): <i>16,974</i>	
DOM position 7	DOM id: UP <u>5H0134</u>	
(U, Short) Cable mark: 883		
<ul> <li>□ Bottom shackle connected</li> <li>□ Top clutch connected at link #_ 20 Δ(7-1)</li> <li>□ Bow OK → □ clutch zip tied</li> <li>Photos: □ phi orientation □ whole view</li> </ul>	-8): <u> { ,888</u>	
Breakout 4	Time:	
	Now 5:24  Last b/o Δt [min]  Depth: Paro 907.30  Keller 907.85  Payout 983.05	
□ All clear to lower cable ⊚		





Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)		
DOM position 6	DOM id: TP <u>6P1275</u>	
(T, Long) Cable mark: 900  Bottom shackle connected	A(C.7). 1/ 93/	
✓ Top clutch connected at link # $_/8$ ✓ Bow OK $\rightarrow$ ✓ clutch zip tied Photos: $\Box$ phi orientation $\Box$ whole view	Δ(6-7): <u>16,931</u>	
DOM position 5 (U, Short) Cable mark: 917	DOM id: UP <u>5 P0 70</u> 0	
Bottom shackle connected  Top clutch connected at link #_20  Bow OK → Clutch zip tied  Photogy □ who exicutes a whole view	Δ(5-6): /6,933	
Photos: □ phi orientation □ whole view		
Breakout 3	Time:	
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now <u>5:33</u> Last b/o  Δt [min]  Depth:  Paro <u>941,51</u> Keller <u>942.02</u>	
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Payout 9/6,37	
☐ Loose pigtails taped to cable		
□ All clear to lower ca	ble ☺	





Photos: DOM ids (☐ long ☐ short); connectors	s (□ long □ short)
DOM position 4 (T, Long)  Cable mark: 934 934	DOM id: TP 6/4287 bent horners so we repticel, 540143
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #/8</li> <li>☑ Bow OK → ☑ clutch zip tied</li> <li>Photos: ☐ phi orientation ☐ whole view</li> </ul>	Δ(4-5): 16.977 16.948
DOM position 3 (U, Short) Cable mark: 951	DOM id: UP <u>6 f /380</u>
<ul> <li>☑ Bottom shackle connected</li> <li>☑ Top clutch connected at link #</li></ul>	Δ(3-4)
Breakout 2	
- LongDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	La: \( \Delta t \)
- ShortDOM  □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Payout 949,83
☐ Loose pigtails taped to cable	
	я
□ All clear to lower ca	able ©
_ All clear to lower ce	



No second Paro no more...

icecube String Deployment Lo	og	Ouring 40	
Photos: DOM ids ( $\square$ long $\square$ short); connectors ( $\square$ long $\square$ short)			
DOM position 2	DOM id: T	P 5H0/3/	
(T, Long) Cable mark: 968			
<ul> <li>Bottom shackle connected</li> <li>Top clutch connected at link #_/8</li> <li>Bow OK → □ clutch zip tied</li> <li>Photos: □ phi orientation □ whole view</li> </ul>	Δ(2-3):		
DOM position 1	DO	30	
U, Short)  Cable mark: 984  Bottom shackle connected  Top clutch connected at link #_20  Bow OK → □ clutch zip tied  Photos: □ phi orientation □ whole view	Δ(1-2):	Could	
Breakout 1		Time:	
	Now 6:	06	
- LongDOM	Last b/o		
☐ connector O-ring in place and ☐ lub			
□ breakout O-ring in place and □ lube	C PROVI	Depth:	
□ connected	Paro <u>//</u> Keller /	1016 32	
- ShortDOM	Payout 6	183.19	
□ connector O-ring in place and □ lube □ breakout O-ring in place and □ lube □ connected	ped	10-711-	
☐ Loose pigtails taped to cable		d)	

Group photo

☐ All clear to lower cable ☺



### **Uphole Pressure Sensor (Setra)**

After DOM1 is safely under the surface (> 50 m)

	Time: 6:/6
Stop the cable winch	
☐ Lower Setra pressure sensor into hole	· · · · · · · · · · · · · · · · · · ·
☐ Distance to Setra from floor:	
Setra readout verified with monitoring system	n
Well depth from Setra:	
□ Well depth from laser: <u>44.831</u>	*
If the two well depth measurements agree:	
☐ Switch to Setra well depth in monitoring system	n
	Time:

Now the String Drop begins



<b>String</b>	Drop
---------------	------

#### The target depth is 2450 m

☐ Switch cable	e winch to compu	iter control	
□ Speed:	Time:	Depth:	
□ Speed:	Time:	Depth:	
☐ Speed:	Time:	Depth:	
☐ Speed:	Time:	Depth:	
☐ Speed:	Time:	Depth:	
☐ Speed:	Time:	Depth:	

Danth Manitoring (log on the fly - do not stop for this)

Depth worthorning (log on the hy – do not stop for this)				
Time	Well depth <sup>1</sup>	Depth by cable marks <sup>2</sup>	Depth by Payout <sup>1</sup>	Δdepth P-K¹
	The state of the s			The state of the s
7:05	44.316	1974	1958.18	-1.13
7:20	43.196	2173	2153.60	-0.57
7:40	42,874	2417	2395.00	-0.60
	7:05 7:20	Time Well depth <sup>1</sup> 7:05 44.3/6 7:20 43.196	Time Well depth¹ Depth by cable marks²  7:05 44.3/6 1974  7:20 43.196 2173	Time Well depth¹ Depth by cable marks² Depth by Payout¹  7:05 44.3/6 1974 1958.18  7:20 43.196 2173 2153.60

¹Read off monitoring screen

<sup>2</sup>Caple mark offset =  $\frac{1}{5}$  (at DOM59) -  $\frac{1}{2}$  m =  $\frac{-16.361}{2}$  (at DOM60) (from p.4)2445.11

- ☐ Switch to manual control @ 2400 m
- ☐ Well depth

@ 2420: —

@, 2440: 42,874

Position string at target depth of 2450 m

Time: 7:40

String secured with Yale grip and anchor chain Time: 8.0/

1999.84

2199.69





<b>Absolute</b>	depth	with	bottom	Paro
	3.55			

(depth in meters and pressure in PSI)

☐ Distance from Paro to DOM60:

 $d_{Paro-DOM60} = (d_{Paro-DOM59} + 17) m = 18.607 \leftarrow insert below$ 

☐ Convert Paro pressure to string depth:

 $K = 3.78151 \cdot 10^{-6}$  /PSI (compressibility of aerated water)

use 6 decimals for exp's)

Ambient pressure (from p. 4):  $P_0 =$ \_\_\_\_\_PSI  $\rightarrow \exp(-KP_0) =$ \_\_\_\_\_

Pressure reading (from screen):  $P = \underline{\hspace{1cm}} PSI \rightarrow exp(-KP) = \underline{\hspace{1cm}}$ 

Subtract exponentials → = \_\_\_\_

 $\times$  1.85947·10<sup>5</sup>

Paro depth in water  $\rightarrow$  = \_\_\_\_\_ m

Add distance to DOM60 (above) -- + \_\_\_\_\_ m

Add well depth  $\rightarrow$  + \_\_\_\_\_ m

Depth of bottom DOM  $\rightarrow$  = \_\_\_\_\_ m

### Final depth estimates

◄----- read off deployment screen ------

Time:	Paro	Keller	Payout	Cable marks
Reading	3424,90 PSI	2678.35 PSI	2587.8/ m	2423 m
Offset	9,44 PSI	-/6.30 PSI	186.95 m	-16.361 m
Well depth		m	This space is intentionally left blank	
Dist. to DOM60	18.609 m	527.706 m		
DEPTH (DOM60)	2451,04	2451.63	2460.86	2439.361

Time: 8:01

Final depth (DOM60): 2451.64



Deployment Closeout	
Log entries complete	
String safely secured	
String safety secured	
☐ Hole covered and secured	
Equipment safely shutdown and secured	
Deployment data OK (in database)	
Site cleanup	
Deployment crew dismissed	
String deployment complete	
Time 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
Time: 8:01 Date: 1/29/07	
Shift Lead:	
Logger: My Hyp Ing	
PTS Lead: M& Agotina	
name / signature	
Deployment Manager: John Ton Jan Jan Jan John Jan	
Safety Officer: Property Name / signature	
nume i signature	
IceCube On-ice Lead:	
name / signature	



## IceCube Deployment Monitoring Check Sheet (IDMCS)

# Version 4.0 December 12, 2006

#### Kurt Woschnagg, UCB

#### **General instructions**

- ▶ Read through this entire document before deployment starts.
- ▶ Deployment monitoring is done with a computer (housed in the TOS) running drill/deployment monitoring software (by Chuck Rentmeesters) with a GUI for readout and manual inputs. All deployment sensor data and manual inputs are logged and saved on disk by this system.
- ▶ For each manual entry into the monitoring interface (marked **ENTER** below), also make a note in the logbook (marked *Logbook* below).
- ▶ For each entry in the logbook, include time and name (initials).
- ▶ Write down as much useful information you can think of (it will all be needed sooner or later).

#### Measurement instructions

- ▶ All vertical measurements are relative to the floor of the tower (not the lip of the kick board).
  - Measure well depth from this level.
  - Take cable mark readings at this level.
- ▶ The location of a DOM on a string (for distance measurements) is defined as the position of the center of the sphere (at the equator defined by the harness).
- ▶ When taking a cable mark reading, estimate the location to nearest cm (0.01 m) with closest cable marks and tape measure.
- ▶ The location of a Paro is defined at the bottom of its body (at the little hole with the nipple).
- ▶ The location of a Keller is defined at the row of holes in the black plastic nose cap.
- ▶ The distance between a pressure sensor and the nearest DOM is positive/negative if the unit is above/below the DOM.
- ▶ Well depth is measured with a laser ranger (if possible), or with a tape measure (if not).
- ▶ The unit used for all distances and depths during deployment is meters.

## Screen Tab: TOS ▶ Deployment

### Sensors/Graph

This is the main tab used during deployment monitoring. No input required on this tab.

Pressure/Depth of String

Current and ambient (air) pressures, and the corrected depths at DOM60.

Spacing/Depth Comparison Difference in depth from pressure data. Should be stable during deployment!

Velocity

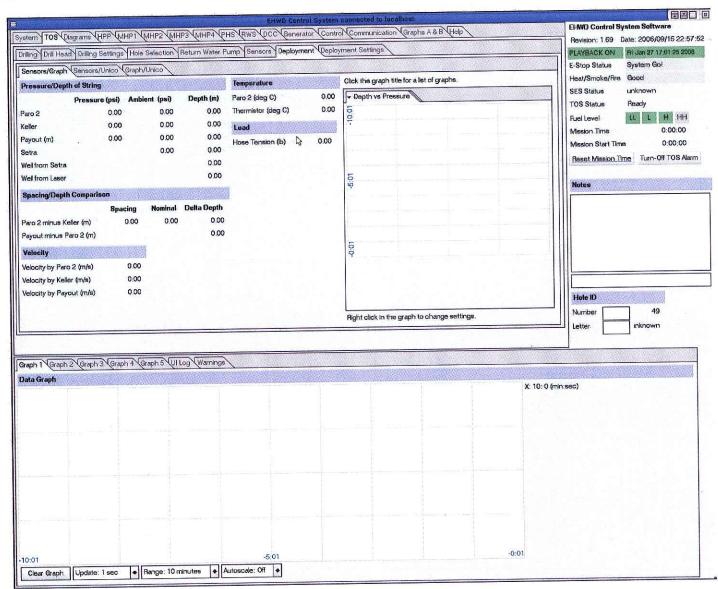
The deployment velocity calculated from recent pressure/payout readings.

**Temperature** 

Temperature readings.

Load

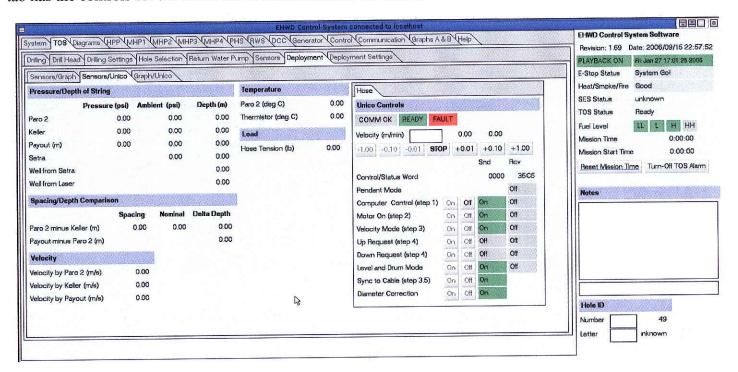
Cable tension from load cell data.



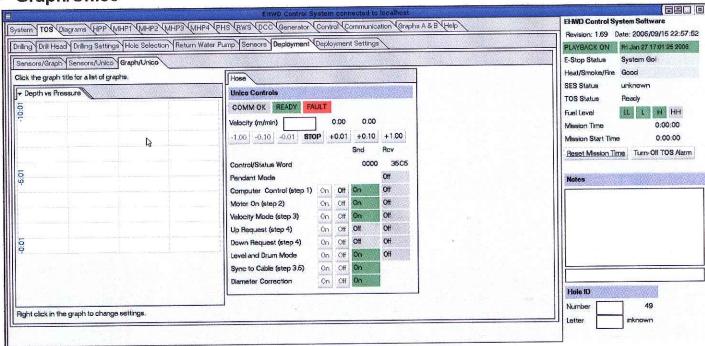
## Screen Tab: TOS ▶ Deployment

#### ▶ Sensors/Unico

This tab has the same data display as the main Sensors/Graph tab above, but instead of the graph window this tab has the controls for the Unico drive which controls the winch.



▶ Graph/Unico



## Screen Tab: TOS ▶ Deployment Settings

#### Settings

This is the main tab for entering information that is needed for a correct depth calibration of the pressure data. Make sure you understand what all the entries mean before deployment starts.

**Tower Mode** 

Click on "Deployment".

**Deployment Events** 

Click the appropriate button when one of the predefined events occurs (see list below).

**DDB** Mode

Select the correct DDB ID before deployment startup (needed for Keller calibration).

Payout at Tower

Reset payout when bottom DOM is at tower floor level.

Well Depth Selection Select source of well depth used in depth calculation.

**Ambient Pressures** 

Press "Get" when pressure sensor is attached to cable, or enter reading at that time.

**Nominal Spacing** 

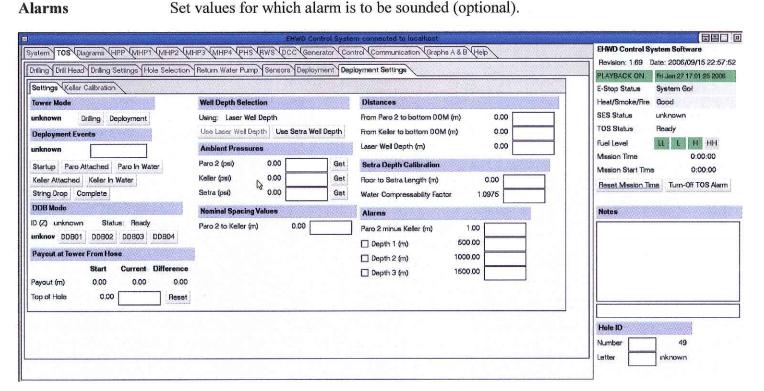
Enter calculated distance between Paro and Keller.

**Distances** 

Enter calculated distances between Paro/Keller and DOM60, and well depth.

Setra Depth Calib.

Enter measured length of Setra cable, from floor to sensor.



## **Deployment Events**

☐ Startup

Click when the deployment begins.

☐ Paro Attached

Click when the Paro is attached to the breakout and starts sending data.

Paro In Water

Click when the Paro reaches the water.

Keller Attached

Click when the Keller is attached to the breakout and starts sending data.

☐ Keller In Water

Click when the Keller reaches the water.

☐ String Drop

Click when the String Drop phase begins, after all DOMs have been attached.

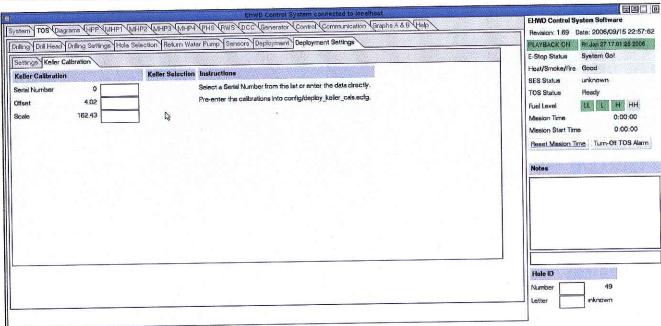
☐ Complete

Click when the deployment ends (string is secured, etc).

## Screen Tab: TOS ▶ Deployment Settings

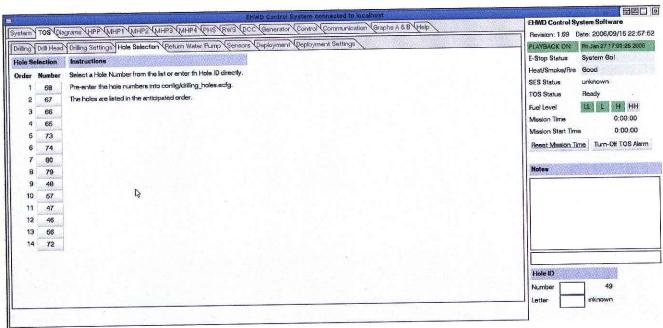
#### ▶ Keller Calibration

On this tab you select the Keller ID by clicking on the appropriate button. The correct (pre-programmed) calibration constants will then be used for the Keller pressure reading.



## Screen Tab: TOS ▶ Hole Selection

On this tab you select the hole/string number, either by clicking on the numbered button on the left or by entering it in the "Hole ID" field in the lower right hand corner.



#### Distances between devices

### calculate manually and enter on Deployment Settings tab

Distance between Paro and DOM60:	=
Distance between Keller and DOM60:	 =
Distance between Paro and Keller:	=

### Notes:

There are 60 DOMs on every string.

The nominal spacing between DOMs is 17 m.

The nominal spacing between breakouts is 34 m.

Breakouts (1-30) and DOMs (1-60) are counted from the top.

The Keller is at breakout 15, just above DOM29.

The Paro is at breakout 30, just above DOM59.

(Fun Fact: There used to be a second Paro at breakout 1 on the first four strings)

#### **Pressure conversions**

		PSI	mH <sub>2</sub> O	Atm
1 PSI	=	1	0.70	0.07
1 mH <sub>2</sub> O	=	1.4	- 1	0.1
1 atm	=	14.7	10.3	1

## **Check Sheet**

		56%
	STRING	#
DATE.		

	Before Deployment	
9	Action: Locate laser ranger for well depth measurements.	
	Action: Locate metric tape measure.	
	Action: Locate one Paro and one Keller, plus spares of each.	
	Action: Locate bucket (for cooling of Keller sensor with water/ice mix).	
	Action: Fill bucket with snow and place in heated area to make slush.	
	Action: Locate Setra uphole pressure assembly (sensor + cable).	

## Deployment Startup

	Action: Click "Deployment" button under "Tower Mode" on Deployment Set	tings tab
	Action: Select string (=hole) number on Hole Selection tab.	
	Action: Note deployment start time.	
	Logbook: Time	
/		

Action: Click "Reset Mission Time" on the right panel on the deployment screen.

Action: Click "Startup" under Deployment Events.

IceCube String Deployment Monitoring
Action: Note DDB id number (1, 2, 3, or 4).
ENTER: DDB# (select button)
Logbook: DDB#
Action: Take a well depth measurement with the laser ranger.
ENTER: Well depth [m] 5-2.598
Logbook: Well depth
Action: Reset Payout when DOM60 breaks the plane of the floor.
CLICK: "Reset" button (Top of Hole Reset) on Deployment Settings ▶ Settings tab.
Logbook: Payout Start value 186.96 > 0
Action: Get cable mark reading at DOM59.
Logbook: Cable mark [m]
Action: Attach Paro at breakout #30. (This is called "Paro2" on the monitoring screen).
Logbook: Paro serial number
Action: Click "Paro Attached" under Deployment Events.
Action: Measure distance between Paro location and nearest DOM.
Estimate distance to <i>bottom</i> DOM by adding $n$ 17-meter segments $(n \text{ should be } 1 \text{ for the Paro since nearest DOM is #59}).$
ENTER: Distance [m] from Paro to bottom DOM (#60)
Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

Action: Get cable mark reading at Paro.

Logbook: Cable mark [m]



## IceCube String Deployment Monitoring

Action: Take Paro air pressure reading just before it breaks the water surface.

**ENTER**: Ambient pressure [PSI] for Paro

Logbook: Paro2 air pressure

## **During Deployment**

Action: Click "Paro In Water" under Deployment Events.

Action: Measure curved distance of main cable going around DOM (for at least two DOMs).

Logbook: Straight (vertical) distance for DOM segment, curved cable distance

Action: Measure real distance between neighboring DOMs (for every pair) with laser ranger.

Logbook: DOM#'s, distance

Action: Put Keller (and one spare) in bucket of water (at near freezing temperature) at least one hour before breakout #15 is reached.

Note: The Keller is not temperature corrected and must therefore be brought to the temperature of the water in the hole (0-2°C) before the air pressure offset is determined.

Action: Attach Keller at breakout #15.

**ENTER**: Keller serial number

Logbook: Keller serial number

Action: Click "Keller Attached" under Deployment Events.

Action: Measure distance between Keller and nearest DOM.

Estimate distance to *bottom* DOM by adding n 17-meter segments (n should be 31 for Keller since nearest DOM is #29).

706 +31×17=

ENTER: Distance [m] from Keller to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60



## IceCube String Deployment Monitoring

	Action: Get cable mark reading at Keller.
/	Logbook: Cable mark [m] for Keller
d	Action: Determine Keller air pressure offset before (or just as) Keller hits water.
	ENTER: Ambient pressure [PSI] for Keller
/	Logbook: Ambient Keller pressure
$\forall$	Action: Click "Keller In Water" under Deployment Events.
	Action: Get cable mark reading at top DOM.
/	Logbook: Cable mark [m]
ď	Action: Measure well depth as soon as top DOM is under water.
	ENTER: Well depth [m]
	Logbook: Well depth [m], measurement method (laser/tape)
	Between DOM attachment and String Drop
	Action: Lower Setra assembly into hole (after top DOM is at least 50 m under the surface).
	Action: Measure distance between Setra sensor and floor of tower (distance marked on cable).
	ENTER: Distance Setra to floor [m]
	Logbook: Distance Setra to floor
	Action: Measure well depth with Setra system and laser ranger and compare.
	Logbook: Well depth from Setra [m], well depth from laser [m]
	Action: If the two well depth meaurements agree, switch from laser to Setra in monitoring system.

Logbook: Time

Action: Click "Complete" under Deployment Events.

/	During String Drop
Ø	Action: Click "String Drop" under Deployment Events.
	Action: Measure well depth manually (with laser ranger and/or tape measure).
	(if shift lead allows: repeat several times during drop)
	ENTER: Well depth [m]
/	Logbook: Well depth, measurement method (laser/tape)
	Action: Read cable marks at regular intervals.
	Logbook: Cable mark [m]; depth readings [m] (Paro, Keller); time
L. CONTRACTOR	
	End of Deployment
	Action: Get final pressure readings from Paro and Keller when final depth has been reached.
	Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)
	Action: Get final well depth reading (laser and/or Setra).
	HAS TO BE SIMULTANEOUS WITH FINAL PRESSURE READINGS!
	Logbook: Well depth [m] (laser); well depth [m] (Setra)
	Action: Note deployment end time.